# The answer is blowing in the wind: free flying honeybees can integrate visual and mechanosensory inputs for making complex foraging decisions 

Sridhar Ravi ${ }^{1, *}$, Jair E. Garcia ${ }^{2}$, Chun, Wang ${ }^{1}$, and Adrian Dyer ${ }^{2}$

${ }^{1}$ RMIT University, School of Aerospace, Mechanical and Manufacturing Engineering, Bundoora, 3083, Australia
${ }^{2}$ RMIT University, School of Media and Communication, Melbourne, 3000, Australia

## Corresponding author email

* sridhar.ravi@rmit.edu.au


## SUMMARY STATEMENT

In complex environments free-flying honeybees are able to integrate both visual and wind induced-mechano-sensory cues to make decisions in a way that is suggestive of integrative processing by the brain.


#### Abstract

: Bees navigate in complex environments using visual, olfactory and mechano-sensorial cues. In the lowest region of the atmosphere the wind environment can be highly unsteady and bees employ fine motor-skills to enhance flight control. Recent work reveals sophisticated multi-modal processing of visual and olfactory channels by the bee brain to enhance foraging efficiency, but it currently remains unclear if wind-induced mechano-sensory inputs are also integrated with visual information to facilitate decision making. Individual honeybees were trained in a linear flight arena with appetitive-aversive differential conditioning to use a context setting cue of $3 \mathrm{~m} \mathrm{~s}^{-1}$ cross-wind direction to enable decisions about either a 'blue' or 'yellow' star stimulus being the correct alternative. Colour stimuli properties were mapped in bee-specific opponent-colour spaces to validate saliency, and to thus enable rapid reverse learning. Bees were able to integrate mechanosensory and visual information to facilitate decisions that were significantly different to chance expectation after 35 learning trials. An independent group of bees were trained to find a single rewarding colour that was unrelated to the wind direction. In these trials wind was not used as a context-setting cue and served only as a potential distracter in identifying the relevant rewarding visual stimuli. Comparing between respective groups shows that bees can learn to integrate visual and mechano-sensory information in a non-elemental fashion, revealing an unsuspected level of sensory processing in honeybees, and adding to the growing body of knowledge on the capacity of insect brains to use multi-modal sensory inputs in mediating foraging behaviour.


## INTRODUCTION

In natural environments there is an enormous amount of sensory information that needs to be either processed, or ignored, in order for an animal to make accurate decisions (Paulk et al., 2014; Posner et al., 1980; Sareen et al., 2011). Honeybees have emerged as an important biological model for understanding signal-receiver relationships because their goal(s) can be well mapped (Dyer and Arikawa, 2014; Morawetz and Spaethe, 2012; Von Frisch, 1967). The constrained brain size of about one million neurons in bees means that efficient solutions have evolved to seemingly complex problems (Srinivasan, 2010). The large existing body of knowledge on the neurobiology of bees, combined with accessible neural structures, has provided for significant insights into the means of information processing in insect brains (Paulk et al., 2014; Scholl et al., 2014).

To efficiently collect nectar from flowers bees must often fly in challenging conditions with frequent changes in climate, local weather conditions (Ravi et al., 2013) and foraging patch complexity (Steffan-Dewenter and Kuhn, 2003). The Atmospheric Boundary Layer is the lowest region of the atmosphere and it contains the natural habitat of most flying insects. Within this region the wind environment is highly variable, consisting of rapid and unpredictable changes in air speed and direction (Stull, 1988). While these conditions are unfavourable for flight, bees do fly stably and make accurate decisions to orientate, avoid obstacles, or land on surfaces like flowers (Mirwan and Kevan, 2015; Srinivasan, 2010). Free-flying insects are endowed with a variety of sensory systems to achieve areal locomotion, and also use fine motor-skills to maintain flight stability in adverse winds (Ortega-Jimenez et al., 2013; Ravi et al., 2013; Vance et al., 2013).

The role of optic flow in guiding insects to distant targets and flight stabilization has been well documented (Srinivasan, 2014; Srinivasan et al., 2000). Insects also receive information from sensory systems other than vision including olfactory, inertial and mechano-sensors that are likely to aid flight control and navigation. The antennae have been identified as a key wind-encoding organ in insects such as fruit flies, locusts and honeybees (Budick et al., 2007; Gewecke, 1970;

Taylor et al., 2013). The Johnston's organ present in the antenna's pedicle contains strain sensitive sensilli (mechanosensors) that are responsible for converting the deflection of flagellum due to the airborne oscillations (wind or acoustic) into neural signals (Yorozu et al., 2009). Other organs that are believed to aid in wind perception include the Bhom's bristles (Sane, 2009) and hairs on the head (Alexander, 2004). While airborne, insects potentially use information from multiple sensory modalities synergistically to aid flight-control, and recent research in fruit flies (Drosophila) has revealed that wind information from the antennae is combined with inertial and visual signals to provide a stable sensory platform (Fuller et al., 2014). A relationship has also recently been observed in honeybees where vision was shown to combine with wind perception in order to perform abdomen-righting manoeuvres (Taylor et al., 2013). However, relatively limited information currently exists on the operational mechanics of wind-sensitive organs and the neural pathways that may enable integration of mechano-sensory information with other sensory modalities.

Apart from providing information used for flight control, visual sensory systems also play a vital role in modulating decision-making behaviours in honeybees. Bees have a trichromatic (UV-, Blue-, Green- sensitive) visual system allowing for fine colour (Avarguès-Weber et al., 2010; Dyer et al., 2011; Peitsch et al., 1992) and spatial (Avarguès-Weber et al., 2015; Giurfa et al., 1999) discrimination. Bees also possess a capacity to accurately sense olfactory cues (Giurfa and Sandoz, 2012), and a capacity to perceive tactile cues on flowers via by mechano-receptive sensilla trichodea (Erber et al., 1998; Kevan and Lane, 1985).

Interestingly, the honeybee brain shows evidence of allowing multi-modal perception between visual and olfactory sensory inputs (Reinhard et al., 2004b). Multi-modal processing involving both visual and olfactory stimuli has become an important research topic over the past decade with several studies exploring this new field through both behavioural observations and neural measurements (Goyret, 2010; Hebets, 2011; Leonard and Masek, 2014; Milet-Pinheiro et al., 2015; Partan, 2013). Honeybees trained in a Y-Maze to solve a complex delayed-matching to sample problems in the visual domain can slowly learn this task, and then apply the acquired
rule to solve a novel olfactory presentation of stimuli (Giurfa et al., 2001). Furthermore, bees have been shown to use visual and olfactory information in ecologically relevant foraging scenarios as scent can trigger memory for specific colours previously associated with rewarding stimuli (Leonard et al., 2011; Reinhard et al., 2004a; Srinivasan et al., 1998). This suggests that different modalities of sensation may potentially operate synergistically to enhance decision making.

Classically it has been thought that mechano-sensory processing might not require integration with other sensory modalities because in Drosophila, simple visual, tactile and motor memories are processed independent of the mushroom bodies (Wolf et al., 1998). However, a few studies suggest that insects may integrate such sensory channels (Budick et al., 2007), and work on honeybee psychophysics shows that integration of complex information is often experience dependent (Giurfa et al., 2003). Indeed free-flying bumblebees show some evidence of integrating colour and tactile cues (Whitney et al., 2009), or colour and temperature cues (Dyer et al., 2006) when extensive training is provided.

Given the major influence of wind on flight, and the capacity of honeybees to perform multimodal sensory integration depending on the foraging context, we hypothesised that bees are also capable of integrating wind-induced mechano-sensory information with vision to modulate foraging choices. We used an appetitive-aversive differential conditioning paradigm to promote attentional motivation, and we mapped colour salience to allow for some initial understanding of what sensory input into the bee brain may facilitate multi-sensory processing. Wind direction was used as a context-setting cue to predict the colour of the rewarding stimulus, and evaluate whether bees can use colour in a complex environment in a nonelemental fashion (Giurfa et al. 2003; Mota et al. 2011; Young 2011). We additionally explored if bees exhibited a hierarchical preference for either spatial location, or chromatic properties, while making a decision in the context of multi-modal sensory processing of wind and visual stimuli. Finally, to evaluate if multi-modal processing increases sensory load, the learning rates of bees presented with multi-modal sensory integration task were compared with
an independent group that were presented with a simple elemental colour learning task in the presence of wind distracter.

## MATERIALS AND METHODS

## Experimental set-up

Honeybee colonies were maintained 30 m from a feeding site where a gravity feeder provided ad . lib. $10 \%$ sucrose solution. Individual foragers were subsequently recruited and trained using 25 \% sucrose solution to return to a testing site located 10 m away from the gravity feeder. Each honeybee was trained to enter a flight apparatus through a 1.5 cm wide and 10 cm long plexiglass tube that contained gates to control bee movements. Test bees attained flight upon entering the flight apparatus $(0.4 \times 0.3 \times 0.25 \mathrm{~m})(1 \times \mathrm{h} \times \mathrm{w})$ which contained a meshed roof to permit natural lighting and minimize turbulence when the side-wind stimulus was applied. The floor and side walls were lined with 'green' paper, which constituted the visual background for the coloured targets (Fig. 1).

A custom-made cross-wind generator consisting of 6 cm fans was embedded into both side walls near the inlet of the arena (Fig. 1). The fans of the wind generator were placed on opposite sidewalls of the flight tunnel and operated in a synchronous direction, thus allowing air to flow across the flight arena with minimal overall turbulence (Fig. 1). The wind generator produced a steady cross-wind of $\left(3 \mathrm{~m} \mathrm{~s}^{-1}\right)$, measured with a hand-held anemometer, representing an intermediate cruising velocity for bees (Riley et al., 1999).

The experiment stimuli consisted of a target and a distracter that could be either a‘blue’ (B) or a‘yellow’ (Y) five-point star measuring 7 cm wide, placed vertically at the end of the flight arena. Stars were used as these shapes promote fast initial learning in honeybees (Lehrer et al., 1995). A 30 mm long tube of 15 mm diameter was placed at the centre of each visual stimulus for the bees to land and receive a reward or punishment (Fig. 1). The size of each stimulus subtended a visual angle $>15^{\circ}$ from the region of cross-wind within the flight tunnel, thus promoting chromatic
(colour) processing for decision making in free-flying honeybees (Giurfa et al., 1996). The target stimulus contained a reward of a $10 \mu \mathrm{~L}$ drop of $25 \%$ sucrose solution and the distracter stimulus contained a punishment of a $10 \mu \mathrm{~L}$ drop of 60 mM quinine hemisulphate solution to promote learning in free-flying honeybees (Avarguès-Weber et al., 2010).

The selected colours ensured that the stimuli were easily perceived as being chromatically different considering the colour-opponent processing of honeybees (Avarguès-Weber et al., 2010; Dyer et al., 2011; Peitsch et al., 1992). Perceptual chromatic difference between the colour stimuli was measured in terms of chromatic difference in the hexagon (Chittka, 1992), and the colour-opponent coding (COC) (Backhaus, 1991) colour spaces (Fig. 1b, c, Supp. Mat. S-1). Modelling assumed the 'green' colour as background, a daylight colour temperature of 6500 K (Judd et al., 1964), and spectral sensitivity functions specific for A. mellifera (Peitsch et al., 1992).

## Behavioural training

Prior to experiments, honeybee foragers $(n=20)$ were trained to fly in the flight apparatus by placing a $10 \mu \mathrm{~L}$ drop of $25 \%$ sucrose solution on a landing platform in the centre of two vertically presented and identical 5 cm squares with achromatic stripes placed at the end of the flight tunnel. Once the bees had become used to flying within the apparatus, the achromatic pretraining stimuli were replaced with the experiment stimuli (coloured stars).

For half of the bees $(n=10)$ the relationship between the context setting cross-wind direction and the rewarding colour was linked. For example, wind from the left implied that the reward solution was placed in the yellow stimulus and the blue stimulus contained quinine, whilst if the wind was from the right then the blue stimulus would be rewarding and yellow contained quinine (Fig. 2). The relationship was maintained throughout the entire flight trials for each bee, but was pseudo-randomised across individuals in the group (Fig. 2). During an experiment, after a bee entered the inlet tube leading to the entrance of the flight apparatus where its movement was controlled by gates, the cross-wind generator was engaged, and the reward/punishment solutions
were placed in the corresponding stimuli following the pre-established relationship between wind direction and rewarding colour for the individual. The main arena gate was then opened to allow the bee to start foraging.

Upon becoming airborne, bees flew through the region of cross-wind and had to subsequently choose between the two stimuli to make a correct choice. To enable repeat testing to promote learning in a bee, we used the method developed by Morawetz and Spaethe (2012). While collecting the reward, a second drop of sucrose was placed within a vial at the end of the landing tube to entice a bee to reach the end of the tube. As the bee imbibed the second drop of sucrose solution within the vial, it was possible to carefully move the vial to the entrance of the arena and reintroduce the bee to the inlet tube to enable multiple choices per foraging bout (Morawetz and Spaethe, 2012). While in the inlet tube the gates were closed to momentarily trap the bee, and the stimulus and landing surfaces were cleaned using $30 \%$ ethanol solution. This experimental procedure was repeated but the wind direction was pseudo randomized between flight trials while maintaining the relationship between wind direction and the colour of the stimulus containing the reward. After five flight trials a bee was satiated at which point it returned to the hive; this set of actions was deemed as a foraging bout. A total of seven foraging bouts were performed for each bee (i.e. 35 decisions) in the initial learning phase. In this phase, the location of stimuli remained constant but the reward or punishment changed depending on perceived wind direction to enable us dissecting what hierarchical cue (colour cue or spatial location) bees used to solve this complex problem. A reverse-side contingency test was then performed to establish if spatial or chromatic cues were used by the bees in choosing the rewarding stimulus. In the reverse-side contingency test, the location of the chromatic stimulus was reversed within the arena while still maintaining the relationship between wind direction and rewarding colour, and this test was performed over four feeding bouts (i.e. 20 decisions) for each bee.

After the completion of both the learning and reverse-side contingency tests, a single nonrewarded touch test was performed for 20 choices where each bee did not experience cross-winds within the flight tunnel; but they were presented with the blue and yellow stimuli. A non-
rewarded touch test (Avarguès-Weber et al., 2010) enables the quantification of bee choices for preferring particular visual stimuli; thus providing insights into perception independent of the context-setting cue. Statistical analysis was subsequently performed to investigate the possibility of potential bias in the bees towards a particular stimulus.

For the second group of bees $(n=10)$ the colour of the rewarding stimulus remained constant irrespective of the direction of the cross-wind (Fig. 2b). Half of these bees were trained to blue as rewarding and yellow contained quinine; whilst yellow was rewarding for the other half of these bees. During each trial as the individual bee entered the arena, the reward and punishment was placed in the respective stimuli and the cross-wind was initiated. As the bees attained flight upon entering the apparatus, the cross-wind served as a potential low-level distracter stimulus on the capacity to learn colour information (Dyer, 2006). Thus the bees' capacity to learn the rewarding colour irrespective of cross-wind direction was tested to allow for an assessment of whether elemental or multi-modal learning (as experienced by the first group of bees) occurred at a different rate of performance.

## Flight path recording

The flights of a sample of the bees were acquired using a webcam (Logitech V-UBB39, Switzerland), placed vertically over the flight apparatus. In post-processing the flight paths of the bees were obtained by digitizing the videos using custom scripts written in MATLAB release 2014c (The Mathworks, USA). The raw displacement data of the bees were passed through a 10 Hz fourth order Butterworth low-pass filter to smooth the flight paths. Upon take off the mean duration of the bees to fly through the apparatus was generally $<1.5 \mathrm{~s}$, which is well within the time frame for honeybee retention of working memory for matching to sample-type problems (Zhang et al., 2005).

## Statistical Analysis

The statistical analysis tested the null hypothesis of no effect of training on the bees' performance in the multi-sensory associative tasks by implementing a generalised linear model
(GLM). The model included as a dependent variable the percentage of correct choices made by the $n=10$ bees over every 5 trials for each of the seven bouts that consisted of the training phase. The GLM assumed binomially distributed errors and a logit link function. All analyses were performed using the routine glm available in the R statistical software v.3.1.5. (Core Team R, 2015). Similar methods have been used in other studies to test learning in bees (Dyer and Garcia, 2014b) while further information on the statistical technique can be found in (Faraway, 2006).

The effect of the number of flight trials on the decision performance between the group of individuals $(\mathrm{n}=10)$ that were presented with a multi-modal sensory association problem and the group of individuals $(\mathrm{n}=10)$ presented only with the visual problem, was analysed by means of an ANCOVA fitted with a Generalised Linear Model (GLM). The model included the percentage of correct choices ( $p$ ) as dependent variable, number of trials as continuous predictor and perceptual task, i.e. multi-modal vs. visual, as categorical predictor.

## RESULTS

Each individual bee became airborne once they entered the flight apparatus (Fig. 1a) and flew through the region of cross-wind before making a choice between the two chromatic stimuli at the end of the flight arena. Upon encountering the region of cross-wind, the bees typically deviated from the centreline of the arena and flew upstream to traverse the corss-wind, before they realigned with the centreline prior to flying towards the visual stimuli (Fig. 3).

## Effect of learning on bee performance for multi-modal learning group

We found a significant effect of training on the percentage of 'correct' choices ( $p$ ) made by free flying bees after integrating both visual and mechano-sensory information $(z=4.20, \mathrm{P}-$ value $<0.0001$ ) (Fig. 4a).

## Reverse-side contingency test for multi-modal learning group

A reverse-side contingency test was conducted to dissect the possibility that bees use either chromatic (visual) or location (spatial) information to solve the problem of linking the context-setting wind cue with the visual stimuli. At the end of the learning trials, bees selected the correct target with a frequency significantly different from chance (mean probability of 'correct' choices ( $p_{\text {learning }}=0.800$, $\left.\chi_{\text {learning }}^{2}=54.0, \mathrm{P}<0.0001\right)$ ) (Fig. $4 \mathrm{a} \& \mathrm{c}$ ). When the visual stimulus locations were switched in the reverse-side contingency tests, the bees' choices for the correct colour stimulus was significantly higher than chance expectation (Rst) ( $p_{\text {Rst }}=0.753, \chi^{2}$ Rst $=38.5, \mathrm{P}<0.0001$ ). No significant difference was found between the percentages of correct choices at the end of the training phase, and start of the reverse-side contingency test $(z=0.969, \mathrm{P}=0.333)$ (Fig. $4 \mathrm{~b} \& \mathrm{c}$ ), showing that bees use colour as the predicting cue rather than spatial position in the arena. However, these results could have potentially been explained by bees rapidly reverse learning the spatial locations of the cues since they were switched in the reverse-contingency tests, therefore we additionally conducted analyses considering the last choice prior to the reverse-side contingency test ( $p_{\text {learning }}=0.800$ ) to the first choice of each bee after the change ( $p_{\text {Rst }}=0.800$ ). In this case there was also no significant
change in performance $\left(\chi^{2}=0.00, \mathrm{P}=1.00\right)$, confirming that the bees used colour as a cue immediately after the stimuli locations were switched in the test phase.

## Non-rewarded test for multi-modal learning group

In the non-rewarded touch test for multi-modal learning group, in the absence of the context setting cross-wind, the bees chose the yellow stimulus $51.5 \%$ of the time. We found no evidence for preference of this colour over the blue hue option that was significant from chance expectation $\left(\chi^{2}\right.$ $=0.180, \mathrm{P}=0.671)$.

## Evaluation of learning rates between experimental groups

To evaluate the perceptual difficulty of a multi-modal task where both mechano-sensory (wind) and visual information (colour) are processed together for enabling a decision, we compared such a task to independent bees solely learning the colour of a stimulus in the presence of a cross-wind acting as a distracter.

Analyses of the effect of trials across the two groups indicated a significant effect of training in performance for the two groups (Deviance $(G)=14.4, \mathrm{P}=0.0002$ ), and a significant difference in performance resulting from using only visual, or multi-modal information $(G=26.8, \mathrm{P}<0.0001)$. Differences in performance were also observed by the lower number of trials required by the bees to learn the target colour when only visual information was available to solve the visual task (solid red line Fig. 4d), the higher number of correct choices observed when only visual information was associated with the rewarding target during 20 trials $\left(p_{\text {visual }}=0.835\right)$; compared to the performance of the bees trained with the multi-modal condition in the same number of trials $\left(p_{\text {multimodal }}=0.610\right)$.

## DISCUSSION

The understanding of multi-modal sensory processing is a contemporary topic with important insights contributed by recent studies on humans (Morrot et al., 2001), and invertebrates such as honeybees (Leonard and Masek, 2014). In this study we hypothesized that bees are capable of integrating mechano-sensory information with visual stimuli for modulating foraging choice. We sought to assess the capacity of bees to associate mechano-sensory and visual stimuli in a freeflying environment using appetitive-aversive conditioning, which promotes learning during visual association tasks (Avarguès-Weber et al., 2010). The bees had to not only encode the direction of wind, but also use it as a context-setting cue for making a choice between two saliently different colours. To be rewarded, the testing paradigm required bees to reverse learn the rewarding chromatic stimuli in context of the wind cue over multiple flight trials. Previous work shows that honeybees are indeed capable of reverse learning saliently different colours (Von Helversen, 1974) faster than similar colours (Dyer et al., 2014a). Interestingly, an effect of stimulus salience on problem solving is also apparent for olfactory stimuli in honeybees (Mota and Giurfa, 2010).

In our experiment the bees were clearly influenced by the wind as their flight path deviated from the centreline of the test apparatus and individuals tended to orient upstream while they traversed through the region of cross-wind (Fig. 3). Upon exiting the cross-wind region they realigned with the centreline of the flight tunnel prior to making a choice between the two visual stimuli (Fig. 3). Wind profile is critical for not only flight-control but also higher-level decision making as it can influence foraging efficiency and colony level energetics (Heinrich, 2004). In other studies bees have been shown to regulate their flight path over long distances to account for cross-winds when flying to and from foraging sites (Riley et al., 1999). Such flight path corrections would require long time sampling of the wind and one strategy to enable this could be the use of a combination of mechano-sensors that respond to different time scales of wind (Alexander, 2004). The wind profile in the outdoor environment can vary over a wide range, from intermittent gusts to sustained durations of strong winds (Stull, 1988). In our experiment the
bees learnt to associate the direction of the respective 'wind gusts' that would have induced perceivable side forces (Fig. 3) with the visual stimuli. While the sensory systems that are responsible for encoding winds varying over short duration is still unknown, the mechanosensors present in the base of the antennae, Johnston's organ, are likely candidates (Yorozu et al., 2009). Alternatively, the mechano-sensitive Bhom's bristles, present in the base of the antennae provide feedback on the antennae position and could also be responsible for encoding wind-induced deflections of the antennae into relevant sensory inputs (Sane, 2009).

In the non-rewarded touch test, in which there was no context setting cue as a predictor of the correct colour, bees from the multi-sensory learning group chose between the two differently coloured visual stimuli at a level that was not significantly different to chance expectation. This suggests that neither colour preferences (Morawetz et al., 2013), nor acquired associations during the experiments, had caused a colour bias that influenced the findings. This result also confirmed that the bees required the presence of wind as a type of occasion setting cue in order to make accurate colour choices.

The reserve side contingency tests permitted us to test the preference between spatial location and chromatic properties. The cue of colour appears to be more important for honeybees than spatial location in the context of an association with mechano-sensory information, as the success rate of the bees choosing the correct colour would have significantly dropped if spatial location was the cue used during the experiment; but bees preferred to choose stimuli on the basis of colour information (Fig. 4b \& c). This is consistent with recent findings that colour is a more hierarchically represented cue in some spatial shape-processing tasks (Morawetz et al., 2013).

A potential limitation of testing multi-sensory integration in free-flying bees is the possibility that alternative cures may be used to solve a problem. For example, the bees' flight paths may be deviated by the wind in such a way as to only use a spatial visual cue to solve the problem of which stimulus side to choose. To reduce this possibility we used a homogenous visual environment arena where the only salient visual information was the coloured target and distractor stimuli. These
stimuli were also presented at a large visual angle to promote colour vision, whilst reducing reliance on spatial cues (Guirfa et al. 1996; Guirfa et al. 1998). Additionally, the effect of wind shows that the bees actively manoeuvred upstream and then appeared to realign with the centreline of the tunnel prior to decision making about the respective colour stimuli (Fig 3) and if bees were solely relying on spatial cues then their performance in the reverse contingency test would have shown a significant drop, but this did not occur (Fig 4b \& c).

Colour vision is well studied in bees and by ensuring that our visual stimuli promoted colour processing (Sup. Mat. S-1), it is possible to make some initial inferences about potential neural pathways where such signals might project to facilitate integration with mechano-sensory information that would enable the decision making we have observed. Whilst the honeybees' long wavelength sensitive 'Green' photoreceptor signals are first processed in the lamina and probably promote fast achromatic responses to stimuli (Ribi, 1975), useful for flight control, the trichromatic (UV, Blue, Green) receptor signals are initially processed in the outer layers of the medulla, before processing in the inner medulla where there is evidence of colour opponent processing (Dyer et al., 2011; Kien and Menzel, 1977). These processed opponent signals subsequently project both directly to the mushroom body and also to the lobula (Dyer et al., 2011; Yang et al., 2004). Whilst little is currently known about mechano-sensory processing within the brain of bees, there is evidence from Drosophila brains that antenna input, via the wind-sensitive neurons in Johnston's organ, can enable an insect to have complex sensory representations of wind within the brain (Yorozu et al., 2009). As signals from the Johnston's organ do project to the mushroom bodies (Mamiya et al., 2008), this seems a plausible brain structure where both colour visual and mechano-sensory processing could be integrated.

A contemporary question in interpreting multisensory integration which promotes decision making is whether the different channels of information are integrated in either an elemental or nonelemental form. The experiment which tested individual bees learning the saliently different colours in the presence of a 'noise distracter' stimulus of non-predicting wind showed that bees rapidly learn a colour cue to a high level of performance, in a process that is consistent with an associative
mechanism (Fig. 4d). In comparison, when the bees from the group that had to use the wind cue to predict the rewarding colour stimulus, the problem took these bees a significantly more trials to reach similar levels of performance (Fig. 4d). This suggests that learning was not a simple process of interpreting the wind cue in a binary sense that might predict fast and accurate reverse learning of the colour problem, but the brain had to slowly acquire and process the relationships (Fig. 4a). This is consistent with a framework where occasion setting cues are a form of nonelemental processing in bees (Mota et al., 2011), Drosophila (Brembs and Wiener, 2006), and some vertebrates (Bouton and King, 1983; Palmatier and Bevins, 2008; Rescorla et al., 1985). Our results suggest that similar to earlier studies, free-flying bees may also be capable of using wind as an occasion setting cue to facilitate decision making in foraging contexts.

One potential context where the ability to integrate mechno-sensory and visual stimuli may be important is flying in complex environments where wind may affect different species of flowers like tall stemmed daisies or tree based flowers in different ways (Mirwan and Kevan, 2015). Additionally, sensing the wind environment could enhance decision accuracy and speed about which types of flower contain rewards (Burns and Dyer, 2008; Mirwan and Kevan, 2015). This is analogous to the capacity of the bee brain to integrate both colour and olfactory information for reducing uncertainty in decision-making (Leonard et al., 2011). Additionally, the association of wind with certain visual features could also aid in improving flight efficiency, for example by avoiding edges of objects in windy conditions where strong destabilizing jets and gusts can be detrimental to flight. The wind profile can als o have significant influence on the energetics of flight since it is likely that gusty conditions can render flight energetically costly since constant manoeuvres and course corrections are necessary. Thus the ability to consider the prevailing wind profile in making foraging decisions can be beneficial in optimising foraging strategies and improving the energetics of resource acquisition. However our understanding of the influence of mean and transient wind on flight energetics of insects is still limited at present and warrants future work to better understand this complex interaction.

While the evolutionary provenance of the mechanisms supporting the integration of visual and mechano-sensory perceptual channels in aiding foraging decision are still unclear, our results indicate that the bee brain does possess such a capacity, (Fig. 4b). Evolutionary principles suggest that this perceptual capacity would likely eventuate in a miniature brain if such outcomes were of high value to survival. Given the significant influence of wind on energetics of resource acquisition for flying animals, further behavioural and neuro-physiological studies that assess the significance of such sensory integration in improving foraging efficiency in realistic environments will be very useful.

## ACKNOWLEDGMENTS

We thank Scarlett Howard and Lalina Muir for comments on previous versions of the manuscript, Andrew Wootton for maintaining the beehives and Cees Bil for the provision of facilities to conduct the experiments.

## COMPETING INTERESTS

No competing interests declared.

## AUTHOR CONTRIBUTIONS

S.R designed and performed the experiments and wrote the manuscript, J.E.G and S.R. analysed the data and wrote the manuscript, C.W Wrote the paper, A.G.D wrote the manuscript, designed and performed the experiments.

## FUNDING

This work was supported by the Australian Research Council (DP130100015 to A.G.D).

Figures


Figure 1: Details on the experimental set-up. a) Schematic of the flight apparatus used for the experiments. As the bees entered the flight apparatus they experienced a steady cross-wind and were subsequently presented with a 'blue' and 'yellow' stimulus either containing a reward (sucrose) or punishment (quinine). During Learning Trials (LT) the stimulus containing the reward and punishment changed with the cross-wind direction, for example, in the illustration, wind from the right implied reward and punishment were placed in the blue and yellow stimulus respectively and in trials where the wind was from the left, the reward and punishment locations was reversed.

Subsequent to learning trials a Reverse Contingency Test (RCT) was conducted where the location of the stimuli was reversed but the relationship with respect to wind direction was maintained. b) Spectral reflectance curves from the yellow and blue colour targets and the 'green' colour making up the visual background of the flight arena. c) Yellow and blue targets modeled in the colour opponent coding (COC) colour space (Backhaus, 1991), and d) the hexagon colour space (Chittka, 1992). The 'green' colour included in the flight apparatus was as assumed as the 'adapting' hue for colour modeling.

Group 1


Group 2
Learning Trials


Figure 2: Schematic representation of experiments. Group 1: In the learning trial the relationship between wind direction and the rewarding or punishing colour stimuli was linked. Each bee $(n=10)$ experienced 35 learning trials: reward contingency was counterbalanced over the group (upper/lower inserts). After learning a reverse side contingency tests was presented where the left/right position of the stimuli was reversed but the reward contingency for wind direction and colour was retained over the 20 trials. Finally a touch test was conducted with only the two colour stimuli. Group 2: Wind was present but did not act as a predictor of reward colour, and each bee $(n=10)$ had to learn the colour only using a simple associative mechanism. Colour position was pseudo randomised over the 20 learning events, and colour reward contingency for yellow/blue was counterbalanced across the group.


Figure 3: Digitized flight paths of different individual bees through the apparatus during learning trials recorded with overhead camera. Reward was placed in a) yellow and b) blue stimuli respectively. The bees typically flew into the direction of the wind by partially aligning their body with the wind direction as they traversed through the region of cross-wind. Subsequently the bees tended to realign their flight path along the centreline of the tunnel before flying towards the chosen stimuli. To highlight the variation in flight path of the bees due to the cross-wind, the darker line in a) \& b) are flight paths of the same individual bee during two consecutive learning trials when the wind was changed from the right and left respectively.


Figure 4: Learning Performance. a) Solid black line represents the logistic function describing the performance of $n=10$ bees during the discrimination task as a function of training bouts (solid purple points and error bars represent mean and $95 \%$ percentiles among all individuals for each bout). Results indicate that training had a significant effect on bee performance after the 35 trials constituting the training phase ( $\mathrm{P}<0.0001$ ). Dashed lines represent the $95 \%$ confidence intervals of the model and grey lines correspond to logistic functions fitted to data for each individual bee. b) First five choices for each bee of $n=10$ bees for the reverse-side contingency test, performed immediately after bees have completed the training phase. In all instances bees performed higher than the 50 \% chance expectation (dashed line) showing bees transferred information
rather than re-learning the problem. c) Performance in the learning (cross-hatched bar) and reverse-side contingency test (white bar) for the $n=10$ bees employed for the experiment. In both tests the bees chose the target colour for which they have been trained more frequently than expected from chance ( $\mathrm{P}<0.001$ in both cases); however, we found no significant difference in performance between the learning and reverse-side contingency tests $(z=0.969, \mathrm{P}=0.333)$. d) Performance of bees $(n=10)$ selecting the 'correct' target colour in the presence of wind but without integrating information regarding colour, i.e. Decoupled visual and mechano-sentry input, for 20 trials (red line); and, encapsulation of the first 20 trials in a) where visual and mechano-sentry information was coupled (purple line). Training had a significant effect on performance in both cases ( $\mathrm{P}=0.0002$ ), and there is a significant difference in performance for the two different experimental conditions ( $\mathrm{P}<$ 0.0001 ), thus suggesting different levels of perceptual difficulty for each visual task. Error bars indicate standard error of the mean (s.e.m) for proportion data in all cases.

## REFERENCES

Abel, R., Rybak, J. and Menzel, R. (2001). Structure and response patterns of olfactory interneurons in the honeybee, Apis mellifera. J Comp Neurol 437, 363-383.

Alexander, D. E. (2004). Nature's flyers: birds, insects, and the biomechanics of flight. Baltimore, USA: Johns Hopkins University Press.

Avarguès-Weber, A., de Brito Sanchez, M. G., Giurfa, M. and Dyer, A. G. (2010). Aversive Reinforcement Improves Visual Discrimination Learning in Free-Flying Honeybees. PLoS ONE 5, e15370.

Avarguès-Weber, A., Dyer, A. G., Ferrah, N. and Giurfa, M. (2015). The forest or the trees: preference for global over local image processing is reversed by prior experience in honeybees. P Roy Soc Lond B Bio 282, 20142384.

Backhaus, W. (1991). Color opponent coding in the visual system of the honeybee. Vision Res 31, 1381-1397.

Balkenius, A., Bisch-Knaden, S. and Hansson, B. (2009). Interaction of visual and odour cues in the mushroom body of the hawkmoth Manduca sexta. J Exp Biol 212, 535-541.

Balkenius, A., Rosén, W. and Kelber, A. (2006). The relative importance of olfaction and vision in a diurnal and a nocturnal hawkmoth. J Comp Physiol A 192, 431-437.

Bouton, M. E. and King, D. A. (1983). Contextual control of the extinction of conditioned fear: Tests for the associative value of the context. J Exp Psychol Anim B 9, 248-265.

Brembs, B. and Wiener, J. (2006). Context and occasion setting in Drosophila visual learning. Learn Mem 13, 618-628.

Budick, S. A., Reiser, M. B. and Dickinson, M. H. (2007). The role of visual and mechanosensory cues in structuring forward flight in Drosophila melanogaster. J Exp Biol 210, 40924103.

Burns, J. G. and Dyer, A. G. (2008). Diversity of speed-accuracy strategies benefits social insects. Curr Biol 18, R953-R954.

Chittka, L. (1992). The colour hexagon: a chromaticity diagram based on photoreceptor excitations as a generalized representation of colour opponency. J Comp Physiol A 170, 533-543.

Core Team R. (2015). R: A Language and Environment for Statistical Computing. Vienna: R Foundation for Statistical Computing.

Devaud, J.-M., Papouin, T., Carcaud, J., Sandoz, J.-C., Grünewald, B. and Giurfa, M. (2015). Neural substrate for higher-order learning in an insect: Mushroom bodies are necessary for configural discriminations. P Natl Acad Sci USA 112, E5854-E5862.

Dyer, A. G. (2006). Discrimination of flower colours in natural settings by the bumblebee species Bombus terrestris (Hymenoptera: Apidae). Entomol Gen 28, 257-268.

Dyer, A. G. and Arikawa, K. (2014). A hundred years of color studies in insects: with thanks to Karl von Frisch and the workers he inspired. J Comp Physiol A 200, 409-410.

Dyer, A. G., Dorin, A., Reinhardt, V., Garcia, J. E. and Rosa, M. G. P. (2014a). Bee reverse-learning behavior and intra-colony differences: Simulations based on behavioral experiments reveal benefits of diversity. Ecol Model 277, 119-131.

Dyer, A. G. \& Garcia, J. (2014b) Color Difference and Memory Recall in Free-Flying Honeybees: Forget the Hard Problem.Insects, 5, 629-638

Dyer, A. G., Paulk, A. C. and Reser, D. H. (2011). Colour processing in complex environments: insights from the visual system of bees. P Roy Soc Lond B Bio 278, 952-959.

Dyer, A. G., Ravi, S. and Garcia, J. E. (2014c). Flying in Complex Environments: Can Insects Bind Multiple Sensory Perceptions and What Could be the Lessons for Machine Vision? JSEA 7, 406-412.

Dyer, A. G., Whitney, H. M., Arnold, S. E. J., Glover, B. J. and Chittka, L. (2006). Bees associate warmth with floral colour. Nature 442, 525-525.

Ehmer, B. and Gronenberg, W. (2002). Segregation of visual input to the mushroom bodies in the honeybee (Apis mellifera). J Comp Neurol 451, 362-373.

Erber, J., Kierzek, S., Sander, E. and Grandy, K. (1998). Tactile learning in the honeybee. J Comp Physiol A 183, 737-744.

Fahrbach, S. E. (2006). Structure of the Mushroom Bodies of the Insect Brain. Annu Rev Entomol 51, 209-232.

Faraway, J.J. (2006) Extending the Linear Model with R. Chapman \& Hall/CRC, Boca Raton

Fuller, S. B., Straw, A. D., Peek, M. Y., Murray, R. M. and Dickinson, M. H. (2014). Flying Drosophila stabilize their vision-based velocity controller by sensing wind with their antennae. P Natl Acad Sci USA 111, E1182-E1191.

Galizia, C. G. and Kimmerle, B. (2004). Physiological and morphological characterization of honeybee olfactory neurons combining electrophysiology, calcium imaging and confocal microscopy. J Comp Physiol A 190, 21-38.

Gerber, B. and Smith, B. H. (1998). Visual modulation of olfactory learning in honeybees. $J$ Exp Biol 201, 2213-7.

Gewecke, M. (1970). Antennae: Another Wind-sensitive Receptor in Locusts. Nature 225, 1263-1264.

Giurfa, M., Hammer, M., Stach, S., Stollhoff, N., MÜLler-Deisig, N. and Mizyrycki, C. (1999). Pattern learning by honeybees: conditioning procedure and recognition strategy. Anim Behav 57, 315-324.

Giurfa, M., Nunez, J. and Backhaus, W. (1994). Odour and colour information in the foraging choice behaviour of the honeybee. J Comp Physiol A 175, 773-779.

Giurfa, M. and Sandoz, J.-C. (2012). Invertebrate learning and memory: Fifty years of olfactory conditioning of the proboscis extension response in honeybees. Learn Mem 19, 54-66.

Giurfa, M., Schubert, M., Reisenman, C., Gerber, B. and Lachnit, H. (2003). The effect of cumulative experience on the use of elemental and configural visual discrimination strategies in honeybees. Behav Brain Res 145, 161-169.

Giurfa, M., Vorobyev, M., Kevan, P. and Menzel, R. (1996). Detection of coloured stimuli by honeybees: minimum visual angles and receptor specific contrasts. J Comp Physiol A 178, 699709.

Giurfa, M., Zhang, S., Jenett, A., Menzel, R. and Srinivasan, M. V. (2001). The concepts of 'sameness' and 'difference' in an insect. Nature 410, 930-933.

Goyret, J. (2010). Look and touch: multimodal sensory control of flower inspection movements in the nocturnal hawkmoth Manduca sexta. J Exp Biol 213, 3676-3682.

Groh, C. and Rössler, W. (2011). Comparison of microglomerular structures in the mushroom body calyx of neopteran insects. Arthropod Struct Dev 40, 358-367.

Hebets, E. (2011). Current status and future directions of research in complex signaling. Curr Zool 57, i-v.

Heinrich, B. (2004). Bumblebee economics. Cambridge, USA: Harvard University Press.
Judd, D. B., Macadam, D. L., Wyszecki, G., Budde, H. W., Condit, H. R., Henderson, S. T. and Simonds, J. L. (1964). Spectral Distribution of Typical Daylight as a Function of Correlated Color Temperature. J Opt Soc Am 54, 1031-1040.

Kevan, P. G. and Lane, M. A. (1985). Flower petal microtexture is a tactile cue for bees. $P$ Natl Acad Sci USA 82, 4750-4752.

Kien, J. and Menzel, R. (1977). Chromatic properties of interneurons in the optic lobes of the bee. II. Narrow band and colour opponent neurons. J. Comp. Physiol. 113, 35-53.

Kirschner, S., Kleineidam, C. J., Zube, C., Rybak, J., Grünewald, B. and Rössler, W. (2006). Dual olfactory pathway in the honeybee, Apis mellifera. J Comp Neurol 499, 933-952.

Kleyko, D., Osipov, E., Gayler, R. W., Khan, A. I. and Dyer, A. G. (2015). Imitation of honey bees' concept learning processes using Vector Symbolic Architectures. BICA 14, 57-72.

Kriston, I. (1973). Die Bewertung von Duft- und Farbsignalen als Orientierungshilfen an der Futterquelle durchApis mellifera L. J. Comp. Physiol. 84, 77-94.

Lehrer, M., Horridge, G. A., Zhang, S. W. and Gadagkar, R. (1995). Shape Vision in Bees: Innate Preference for Flower-Like Patterns. Philos T Roy Soc B 347, 123-137.

Leonard, A. and Masek, P. (2014). Multisensory integration of colors and scents: insights from bees and flowers. J Comp Physiol A, 1-12.

Leonard, A. S., Dornhaus, A. and Papaj, D. R. (2011). Flowers help bees cope with uncertainty: signal detection and the function of floral complexity. J Exp Biol 214, 113-121.

Mamiya, A., Beshel, J., Xu, C. and Zhong, Y. (2008). Neural Representations of Airflow in Drosophila Mushroom Body. PLoS ONE 3, e4063.

Milet-Pinheiro, P., Ayasse, M. and Dötterl, S. (2015). Visual and Olfactory Floral Cues of Campanula (Campanulaceae) and Their Significance for Host Recognition by an Oligolectic Bee Pollinator. PLoS ONE 10, e0128577.

Mirwan, H. B. and Kevan, P. G. (2015). Motion discrimination by Bombus impatiens (Hymenoptera: Apidae). Can Entomol FirstView, 1-12.

Morawetz, L. and Spaethe, J. (2012). Visual attention in a complex search task differs between honeybees and bumblebees. J Exp Biol 215, 2515-2523.

Morawetz, L., Svoboda, A., Spaethe, J. and Dyer, A. (2013). Blue colour preference in honeybees distracts visual attention for learning closed shapes. J Comp Physiol A 199, 817-827.

Morrot, G., Brochet, F. and Dubourdieu, D. (2001). The Color of Odors. Brain Lang 79, 309-320.

Mota, T. and Giurfa, M. (2010). Multiple Reversal Olfactory Learning in Honeybees. Front Behav Neurosci 4, 48.

Mota, T., Giurfa, M. and Sandoz, J.-C. (2011). Color modulates olfactory learning in honeybees by an occasion-setting mechanism. Learn Mem 18, 144-155.

Mota, T., Gronenberg, W., Giurfa, M. and Sandoz, J.-C. (2013). Chromatic Processing in the Anterior Optic Tubercle of the Honey Bee Brain. J Neurosci 33, 4-16.

Ortega-Jimenez, V. M., Greeter, J. S. M., Mittal, R. and Hedrick, T. L. (2013). Hawkmoth flight stability in turbulent vortex streets. J Exp Biol 216, 4567-4579.

Palmatier, M. I. and Bevins, R. A. (2008). Occasion setting by drug states: Functional equivalence following similar training history. Behav Brain Res 195, 260-270.

Partan, S. (2013). Ten unanswered questions in multimodal communication. Behav Ecol Sociobiol 67, 1523-1539.

Paulk, A. C., Stacey, J. A., Pearson, T. W. J., Taylor, G. J., Moore, R. J. D., Srinivasan, M. V. and van Swinderen, B. (2014). Selective attention in the honeybee optic lobes precedes behavioral choices. P Natl Acad Sci USA 111, 5006-5011.

Peitsch, D., Fietz, A., Hertel, H., Souza, J., Ventura, D. and Menzel, R. (1992). The spectral input systems of hymenopteran insects and their receptor-based colour vision. J Comp Physiol A 170, 23-40.

Posner, M. I., Snyder, C. R. and Davidson, B. J. (1980). Attention and the detection of signals. J Exp Psychol Gen 109, 160-174.

Ravi, S., Crall, J. D., Fisher, A. and Combes, S. A. (2013). Rolling with the flow: bumblebees flying in unsteady wakes. J Exp Biol 216, 4299-4309.

Reinhard, J., Srinivasan, M. V., Guez, D. and Zhang, S. W. (2004a). Floral scents induce recall of navigational and visual memories in honeybees. J Exp Biol 207, 4371-4381.

Reinhard, J., Srinivasan, M. V. and Zhang, S. (2004b). Olfaction: Scent-triggered navigation in honeybees. Nature 427, 411-411.

Rescorla, R. A., Durlach, P. J. and Grau, J. W. (1985). Contextual learning in Pavlovian conditioning. In Context and learning, eds. P. Balsam and A. Tomie), pp. 23-56. Hillside, NJ: Lawrence Erlbaum.

Ribi, W. A. (1975). The neurons of the first optic ganglion of the bee (Apis mellifera). Adv Anat Embryol Cell Biol 50, 1-43.

Riley, J. R., Reynolds, D. R., Smith, A. D., Edwards, A. S., Osborne, J. L., Williams, I. H. and McCartney, H. A. (1999). Compensation for wind drift by bumble-bees. Nature 400, 126126.

Sane, S. P. (2009). Sensory coordination of insect flight. Bangalore, India: TATA Institute of Fundamental Research.

Sareen, P., Wolf, R. and Heisenberg, M. (2011). Attracting the attention of a fly. P Natl Acad Sci USA 108, 7230-7235.

Scholl, C., Wang, Y., Krischke, M., Mueller, M. J., Amdam, G. V. and Rössler, W. (2014). Light exposure leads to reorganization of microglomeruli in the mushroom bodies and influences juvenile hormone levels in the honeybee. Dev Neurobiol 74, 1141-1153.

Srinivasan, M. (2014). Going with the flow: a brief history of the study of the honeybee's navigational 'odometer'. J Comp Physiol A 200, 563-573.

Srinivasan, M. V. (2010). Honey Bees as a Model for Vision, Perception, and Cognition. Annu Rev Entomol 55, 267-284.

Srinivasan, M. V., Zhang, S., Altwein, M. and Tautz, J. (2000). Honeybee navigation: Nature and calibration of the 'odometer'. Science 287, 851-853.

Srinivasan, M. V., Zhang, S. W. and Zhu, H. (1998). Honeybees link sights to smells. Nature 396, 637-638.

Steffan-Dewenter, I. and Kuhn, A. (2003). Honeybee foraging in differentially structured landscapes. P Roy Soc Lond B Bio 270, 569-575.

Strausfeld, N. J., Hansen, L., Li, Y., Gomez, R. S. and Ito, K. (1998). Evolution, Discovery, and Interpretations of Arthropod Mushroom Bodies. Learn Mem 5, 11-37.

Stull, R. B. (1988). An introduction to boundary layer meteorology. Dordrecht, The Netherlands: Springer Science \& Business Media.

Taylor, G. J., Luu, T., Ball, D. and Srinivasan, M. V. (2013). Vision and air flow combine to streamline flying honeybees. Sci Rep 3.

Vance, J. T., Faruque, I. and Humbert, J. S. (2013). Kinematic strategies for mitigating gust perturbations in insects. Bioinspir Biomim 8, 016004.

Von Frisch, K. (1967). The dance language and orientation of bees. Cambridge, USA: Harvard University Press.

Von Helversen, O. (1974). Das Experiment: Dressurversuche mit Bienen. Biol Unserer Zeit 4, 119-124.

Whitney, H. M., Chittka, L., Bruce, T. J. A. and Glover, B. J. (2009). Conical Epidermal Cells Allow Bees to Grip Flowers and Increase Foraging Efficiency. Curr Biol 19, 948-953.

Wolf, R., Wittig, T., Liu, L., Wustmann, G., Eyding, D. and Heisenberg, M. (1998). Drosophila Mushroom Bodies Are Dispensable for Visual, Tactile, and Motor Learning. Learn Mem 5, 166-178.

Yang, E.-C., Lin, H.-C. and Hung, Y.-S. (2004). Patterns of chromatic information processing in the lobula of the honeybee, Apis mellifera L. J Insect Physiol 50, 913-925.

Yorozu, S., Wong, A., Fischer, B. J., Dankert, H., Kernan, M. J., Kamikouchi, A., Ito, K. and Anderson, D. J. (2009). Distinct sensory representations of wind and near-field sound in the Drosophila brain. Nature 458, 201-205.

Zhang, S., Bock, F., Si, A., Tautz, J. and Srinivasan, M. V. (2005). Visual working memory in decision making by honey bees. P Natl Acad Sci USA 102, 5250-5255.

